

Valid Inequalities for Mixed Integer Bilevel Linear Optimization Problems

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Attributions

Many current and students contributed to development of this work.

Current and Former Ph.D Students

- Suresh Bolusani
- Scott DeNegre
- Menal Gúzelsoy
- Anahita Hassanzadeh
- Ashutosh Mahajan
- Sahar Tahernajad

Thanks!

Mixed Integer Bilevel Linear Optimization Problems

- *First-level variables:* $x \in X$ where $X = \mathbb{Z}_+^{r_1} \times \mathbb{R}_+^{n_1-r_1}$
- *Second-level variables:* $y \in Y$ where $Y = \mathbb{Z}_+^{r_2} \times \mathbb{R}_+^{n_2-r_2}$

MIBLP

$$\min_{x,y} \{ cx + d^1 y \mid x \in X, y \in \mathcal{P}_1(x), y \in \operatorname{argmin}\{d^2 z \mid z \in \mathcal{P}_2(x) \cap Y\} \}, \quad (1)$$

where

$$\mathcal{P}_1(x) = \{ y \in \mathbb{R}_+^{n_2} \mid A^1 x + G^1 y \geq b^1 \},$$

$$\mathcal{P}_2(x) = \{ y \in \mathbb{R}_+^{n_2} \mid G^2 y \geq b^2 - A^2 x \},$$

Value Function Reformulation

- *First-level variables:* $x \in X$ where $X = \mathbb{Z}_+^{r_1} \times \mathbb{R}_+^{n_1 - r_1}$
- *Second-level variables:* $y \in Y$ where $Y = \mathbb{Z}_+^{r_2} \times \mathbb{R}_+^{n_2 - r_2}$

MIBLP

$$\min_{x,y} \{ cx + d^1 y \mid x \in X, y \in \mathcal{P}_1(x) \cap \mathcal{P}_2(x) \cap Y, d^2 y \leq \phi(b^2 - A^2 x) \},$$

(MIBLP)

where

$$\mathcal{P}_1(x) = \{ y \in \mathbb{R}_+^{n_2} \mid A^1 x + G^1 y \geq b^1 \},$$

$$\mathcal{P}_2(x) = \{ y \in \mathbb{R}_+^{n_2} \mid G^2 y \geq b^2 - A^2 x \},$$

$$\phi(\beta) = \min \{ d^2 y \mid G^2 y \geq \beta, y \in Y \} \forall \beta \in \mathbb{R}^{m_2}.$$

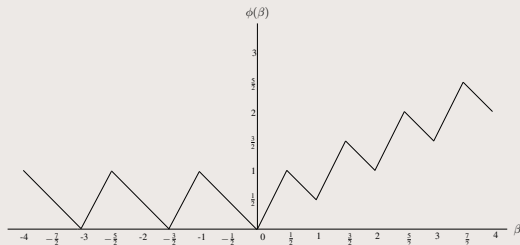
The Value Function

- The second-level *value function* is

MILP Value Function

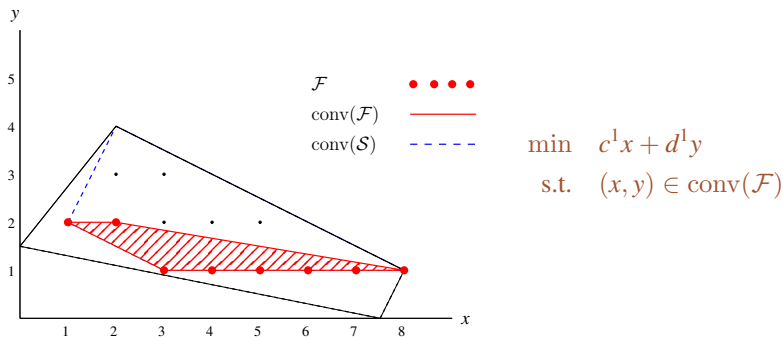
$$\phi(\beta) = \min_{x \in \mathcal{P}_2(\beta) \cap X} c^\top x \quad (\text{VF})$$

for $\beta \in \mathbb{R}^m$. We let $\phi(\beta) = \infty$ if $\beta \in \Omega = \{\beta \in \mathbb{R}^m \mid \mathcal{S}(\beta) = \emptyset\}$.



Polyhedral Reformulation

Convexification considers the following conceptual reformulation.



- This reformulation leads to a similar branch-and-cut algorithm similar to that used for solving MILPs.
- To get bounds, we optimize over a relaxed feasible region.
- We iteratively approximate the true feasible region with linear inequalities.

Branch-and-Cut Algorithm

- The algorithm is based on the framework originally described by DeNegre and Ralphs [2009], but with **many additional enhancements**.
- The algorithm has been implemented in the **MibS** framework, which is open source and available from COIN-OR.
- Details are contained in a forthcoming paper by Tahernejad et al. [2016] (preprint available)

Components

- Bounding
 - **Lower bound** \Rightarrow An LP relaxation strengthened with **valid inequalities**
 - Upper bound \Rightarrow Feasible solutions
- Branching \Rightarrow Several schemes for branching
- Feasibility checking
- Search strategies
- Preprocessing methods
- Primal heuristics

Linking Variables

- The first-level variables with non-zero coefficients in the second-level problem are called the *linking variables* and are indexed by set L .
- **Assumption:** All linking variables are discrete \Rightarrow The optimal value of MIBLP is **attainable**.

For the vectors $x^1, x^2 \in X$ with $x_L^1 = x_L^2$, we have

$$\phi(b^2 - A^2x^1) = \phi(b^2 - A^2x^2)$$

- The **best** bilevel feasible solution (x,y) with $x_L = \gamma \in \mathbb{Z}^L$ can be obtained by solving just one **MILP**.

$$\min \{ cx + d^1y \mid x \in X, y \in \mathcal{P}_1(x) \cap \mathcal{P}_2(x) \cap Y, d^2y \leq \phi(b^2 - A^2x), x_L = \gamma \}$$

(UB)

Lower Bound

Bilevel Feasible Region

$$\mathcal{F} = \{(x, y) \in \mathbb{R}_+^{n_1 \times n_2} \mid x \in X, y \in \mathcal{P}_1(x) \cap \mathcal{P}_2(x) \cap Y, d^2 y \leq \phi(b^2 - A^2 x)\}$$

Two possible relaxations

- 1 Removing the *optimality constraint of the second-level problem*

$$\mathcal{S} = \{(x, y) \in \mathbb{R}_+^{n_1 \times n_2} \mid x \in X, y \in \mathcal{P}_1(x) \cap \mathcal{P}_2(x) \cap Y\}$$

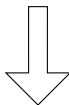
- 2 Removing the *optimality constraint of the second-level problem* and the *integrality constraints*

$$\mathcal{P} = \{(x, y) \in \mathbb{R}_+^{n_1 \times n_2} \mid y \in \mathcal{P}_1(x) \cap \mathcal{P}_2(x)\}$$

Valid Inequalities

Valid inequality: The triple $(\alpha^x, \alpha^y, \beta) \in \mathbb{R}^{n_1+n_2+1}$ is a *valid inequality* for (MIBLP) if

$$\mathcal{F} \subseteq \{(x, y) \in \mathbb{R}^{n_1 \times n_2} \mid \alpha^x x + \alpha^y y \geq \beta\}.$$



Valid improving inequality: The triple $(\alpha^x, \alpha^y, \beta) \in \mathbb{R}^{n_1+n_2+1}$ is a *valid improving inequality* for (MIBLP) with respect to $(\bar{x}, \bar{y}) \in \mathcal{F}$ if

$$\{(x, y) \in \mathcal{F} \mid cx + d^1 y < c\bar{x} + d^1 \bar{y}\} \subseteq \{(x, y) \in \mathbb{R}^{n_1 \times n_2} \mid \alpha^x x + \alpha^y y \geq \beta\}.$$

Cut Generation

- As usual, a *cutting plane* (cut) refers to a valid inequality violated by a given (infeasible) solution to the current relaxation.
- Unlike in MILP, we have several distinctly different classes of solutions with respect to which we might want to generate a cut.
 - ❶ $(\bar{x}, \bar{y}) \notin X \times Y$
 - ❷ $(\bar{x}, \bar{y}) \in X \times Y$, but for which $d^2\bar{y} > \phi(b^2 - A^2\bar{x})$
 - ❸ All $(x, y) \in \mathcal{P}$ with $x_L = \lambda \in \mathbb{Z}^L$
- The set of valid inequalities for MIBLPs can be classified based on the types of the solutions they remove.

Very Rough Classification

- In general, cuts may be generated by separating solutions from a polyhedron obtained by *convexification*.
- Inequalities valid for the following polyhedra correspond roughly to the classes defined on the previous slide.

Classes of inequalities

- Inequalities valid for $\text{conv}(\mathcal{S}) \Rightarrow$ Feasibility Cuts
- Inequalities valid for $\text{conv}(\mathcal{F}) \Rightarrow$ Optimality Cuts
- Inequalities valid for $\text{conv}(\{(x \in \mathcal{F}_1 \mid cx + \Xi(x) < U\}) \Rightarrow$ Projected Optimality Cuts

where

$$\mathcal{F}_1 = \text{proj}_x(\mathcal{F})$$

and Ξ is the so-called “risk” function that captures the impact of the second level decision.

Cut Generation Recipes

Generalized Chvátal Cuts

Theorem 1 If $(\pi^x, \pi^y) \in X \times Y$ is such that $\pi_i^x = 0$ for $i > r_1$ and $\pi_j^y = 0$ for $j > r_2$, $\beta \in \mathbb{Z}$, and $\{(x, y) \in \mathcal{P} \mid \pi^x x + \pi^y y \leq \beta - 1\}$ contains no bilevel feasible solutions, then $\pi^x x + \pi^y y \geq \beta$ is a valid inequality.

Disjunctive Cuts

Theorem 2 Let X_1, X_2, \dots, X_k be a set representing a disjunction valid for \mathcal{F} . Then if $(\alpha^x, \alpha^y, \beta)$ is valid for $\text{conv}(\cup_{1 \leq i \leq k} X_i)$, it is valid for \mathcal{F} .

Intersection Cuts

Theorem 3 Let C be a convex set containing no improving solutions and let (x, y) be an extreme point of \mathcal{P} in the interior of C . Then the intersection cut with respect to C and (x, y) is valid for \mathcal{F} .

- **Feasibility cuts:** This set includes inequalities valid for MILPs.
- **Optimality cuts:**
 - Integer no-good cut [DeNegre and Ralphs, 2009]
 - Intersection cuts [Fischetti et al., 2017]
 - Bound cuts
 - Benders cut [Ralphs et al., 2015, Caprara et al., 2014]
 - Increasing objective cut [DeNegre, 2011]
 - Dual function cuts
- **Projected optimality cuts:**
 - Generalized no-good cut

Integer No-good Cut

Assumptions:

- $r_1 = n_1$ and $r_2 = n_2$.
- Vectors b^1 and b^2 and all matrices A^1, A^2, G^1 and G^2 are discrete.

Theorem 4 Let $(\bar{x}, \bar{y}) \in \mathcal{S} \setminus \mathcal{F}$ be the optimal solution of relaxation problem and H_1 and H_2 denote the set of indices of the first- and second-level constraints, respectively, binding at (\bar{x}, \bar{y}) . Then, under the stated assumptions, we have

$$\alpha^x x + \alpha^y y \geq \beta \quad \forall (x, y) \in \mathcal{F},$$

where

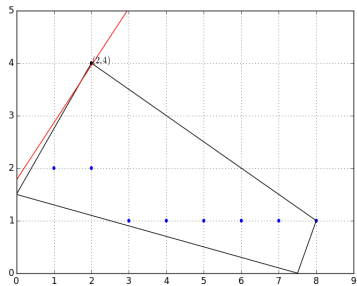
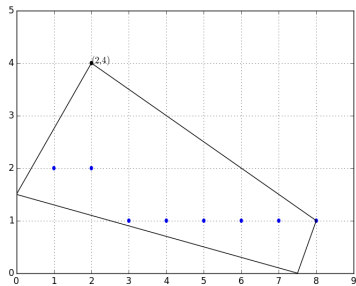
$$\alpha^x = \sum_{i \in H_1} a_i^1 + \sum_{i \in H_2} a_i^2, \alpha^y = \sum_{i \in H_1} g_i^1 + \sum_{i \in H_2} g_i^2, \beta = \sum_{i \in H_1} b_i^1 + \sum_{i \in H_2} b_i^2 + 1$$

and $a_i^1, a_i^2, g_i^1, g_i^2, b_i^1$ and b_i^2 represent the i^{th} rows of A^1, A^2, G^1, G^2, b^1 and b^2 , respectively. Furthermore, we have

$$\alpha^x \bar{x} + \alpha^y \bar{y} = \beta - 1,$$

so the inequality is violated by (\bar{x}, \bar{y}) .

Integer No-good Cut



Benders Cut

Assumptions:

- $x_L \subseteq \mathbb{B}^L$.
- There exists a second-level variable y_i corresponding to each linking variable x_i so that $x_i = 1$ results $y_i = 0$.
- $G^2 \leq 0$.

Theorem 5 Let $(\hat{x}, \hat{y}) \in \mathcal{F}$. Then, under the above assumptions, we have

$$d^2y \leq \sum_{i=1}^{n_1} d_i^2 \hat{y}_i (1 - x_i) \quad \forall (x, y) \in \mathcal{F}.$$

Furthermore, this inequality is violated by all $(x, y) \in \mathcal{S} \setminus \mathcal{F}$ with $x = \hat{x}$.

Increasing Objective Cut

Assumptions:

- $x_L \subseteq \mathbb{B}^L$.
- $A^2 \leq 0$.

Theorem 6 Let $\hat{x} \in X$ and $\hat{y} \in \mathcal{R}(\hat{x})$. Then, under the above assumptions, we have

$$d^2y \leq d^2\hat{y} + M \left(\sum_{i \in L: x_i = 0} \hat{x}_i \right) \quad \forall (x, y) \in \mathcal{F}.$$

Furthermore, this inequality is violated by all $(x, y) \in \mathcal{S} \setminus \mathcal{F}$ with $x_i = 0$ for $\{i \in L \mid \hat{x}_i = 0\}$.

Intersection Cut

Assumption:

- $A^2x + G^2y - b^2 \in \mathbb{Z}$ for all $(x, y) \in \mathcal{S}$.
- $d^2y \in \mathbb{Z}$ for all $(x, y) \in \mathcal{S}$.

Theorem 7 Let $(\bar{x}, \bar{y}) \in \mathcal{S} \setminus \mathcal{F}$ be the optimal solution of the relaxation problem and $\hat{y} \in Y$ satisfy these conditions:

- $d^2\hat{y} < d^2\bar{y}$.
- $G^2\hat{y} \geq b^2 - A^2\bar{x}$.

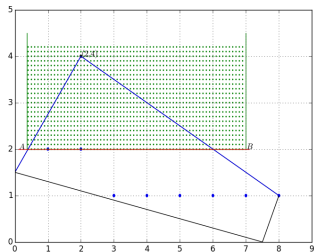
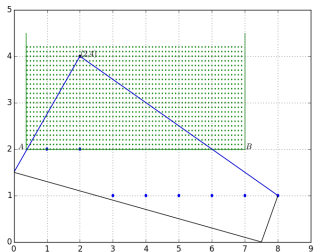
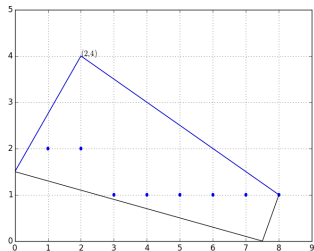
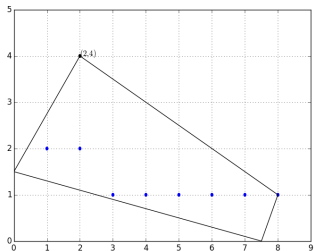
Then, under the stated assumptions, we have

$$\alpha^x x + \alpha^y y \geq \beta \quad \forall (x, y) \in \mathcal{F}, \quad (2)$$

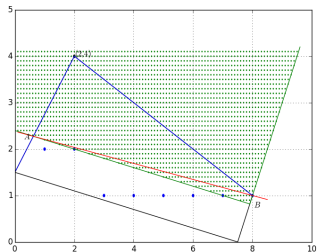
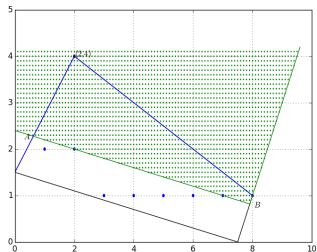
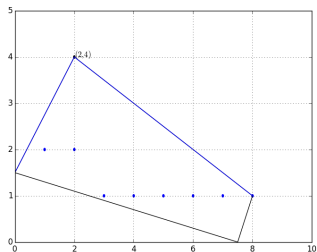
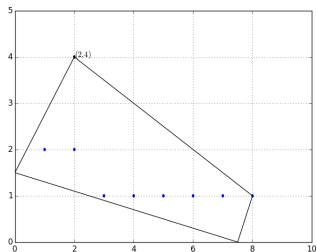
where the inequality (2) is the intersection cut generated associated with (\bar{x}, \bar{y}) and the set

$$\mathcal{C} = \{(x, y) \in \mathbb{R}^{n_1 \times n_2} \mid d^2y \geq d^2\hat{y}, G^2\hat{y} \geq b^2 - A^2x - 1\}. \quad (3)$$

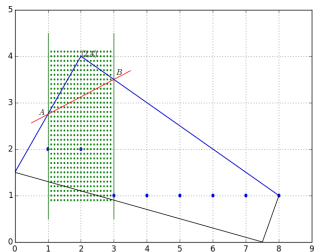
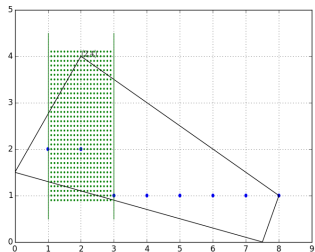
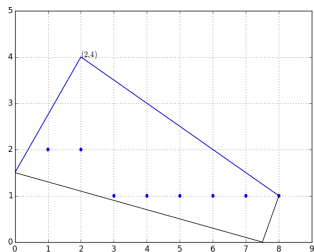
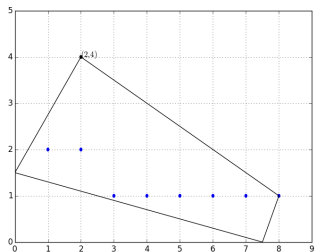
Intersection Cut



Watermelon Intersection Cut



Hypercube Intersection Cut



Generalized No-good Cut

Assumption:

- $x_L \subseteq \mathbb{B}^L$.

Theorem 8 Let $\gamma \in \mathbb{B}^L$. Then, under the desired assumption, we have

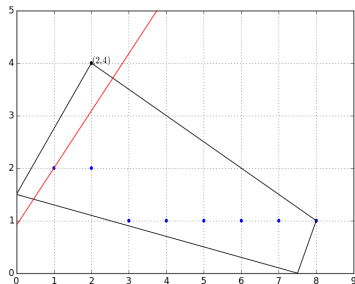
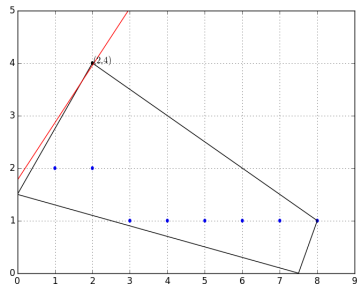
$$\sum_{i \in L: \gamma_i = 0} x_i + \sum_{i \in L: \gamma_i = 1} (1 - x_i) \geq 1 \quad \forall (x, y) \in \mathcal{F} \text{ such that } x_L \neq \gamma. \quad (4)$$

Furthermore, the inequality (4) is violated by all $(x, y) \in \mathcal{P}$ with $x_L = \gamma$.

- The problem (UB) should be solved with $\gamma = \bar{x}_L$ prior to generating this cut.

Strengthening the Valid Inequalities

- **Idea:** A given valid inequality can be strengthened by increasing the value of the RHS.
- Ideally, we can do this until the inequality supports $\text{conv}(\mathcal{F})$.



- However, this need not be done optimally.

The Gauge Function

- The *gauge function* is a function that returns the largest valid right-hand side for an inequality with a given left-hand side vector.

Gauge Function

$$\Gamma(\zeta^x, \zeta^y) = \min_{(x,y) \in \mathcal{F}} \zeta^x x + \zeta^y y \quad (5)$$

- Note that the gauge function is closely related to the value function.
- We have that

$$\alpha^x x + \alpha^y y \geq \Gamma(\alpha^x, \alpha^y) \quad \forall (x, y) \in \mathcal{F}$$

Valid Inequality

An *inequality* defined by $(\alpha^x, \alpha^y, \beta) \in \mathbb{R}^{n_1} \times \mathbb{R}^{n_2} \times \mathbb{R}$ is *valid* for \mathcal{F} if $\beta \leq \Gamma(\alpha^x, \alpha^y)$.

Dual Function Cuts

- The gauge function need not be computed exactly, we only need a bound.
- If $F : \mathbb{R}^{m_1+m_2} \rightarrow \mathbb{R}$ is a *dual function* for the problem (5) (bounds its value function from below), then

$$\alpha^x x + \alpha^y y \geq F(\alpha^1, \alpha^2) \quad \forall (x, y) \in \mathcal{F},$$

where $(\alpha^x, \alpha^y) \in \mathbb{R}^{n_1} \times \mathbb{R}^{n_2} \times \mathbb{R}$.

Strengthened Integer No-Goods

Assumption:

- $x_L \subseteq \mathbb{Z}^L$.

Theorem 9 Let $(\bar{x}, \bar{y}) \in \mathcal{S} \setminus \mathcal{F}$ be the optimal solution of relaxation problem and H_1 and H_2 denote the set of indices of the first- and second-level constraints, respectively, binding at (\bar{x}, \bar{y}) . Then, under the stated assumptions, we have

$$\alpha^x x + \alpha^y y \geq \beta \quad \forall (x, y) \in \mathcal{F},$$

where

$$\alpha^x = \sum_{i \in H_1} a_i^1 + \sum_{i \in H_2} a_i^2, \alpha^y = \sum_{i \in H_1} g_i^1 + \sum_{i \in H_2} g_i^2, \beta = \min_{(x, y) \in \mathcal{F}} \alpha x$$

and $a_i^1, a_i^2, g_i^1, g_i^2, b_i^1$ and b_i^2 represent the i^{th} rows of A^1, A^2, G^1, G^2, b^1 and b^2 , respectively. Furthermore, we have

$$\alpha^x \bar{x} + \alpha^y \bar{y} < \beta,$$

so the inequality is violated by (\bar{x}, \bar{y}) .

MibS software

- is an open-source solver for MIBLPs.
- works based on our branch-and-cut algorithm for MIBLPs.
- is implemented in C++.
- is built on top of the BLIS solver [Xu et al., 2009].
- employs different software available from the *Computational Infrastructure for Operations Research (COIN-OR)* repository
 - *COIN High Performance Parallel Search (CHiPPS)*: To manage the global branch-and-bound
 - *SYMPHONY*: To solve the required MIPs
 - *COIN LP Solver (CLP)*: To solve the LPs arising in the branch and cut
 - *Cut Generation Library (CGL)*: To generate cutting planes within both SYMPHONY and MibS
 - *Open Solver Interface (OSI)*: To interface with other solvers

Computational Results

Table: The summary of data sets

Data Set	First-level Vars Type	Second-level Vars Type	Size	Interdiction
INTERD-DEN	binary	binary	300	yes
IBLP-DEN	discrete	discrete	50	no
IBLP-XU	discrete	discrete	100	no

Computational Results

- Performance of different cuts on the instances of INTERD-DEN
- 199 instances that can be solved by at least one method in 3600 seconds and whose solution time exceeds 5 seconds for at least one method.

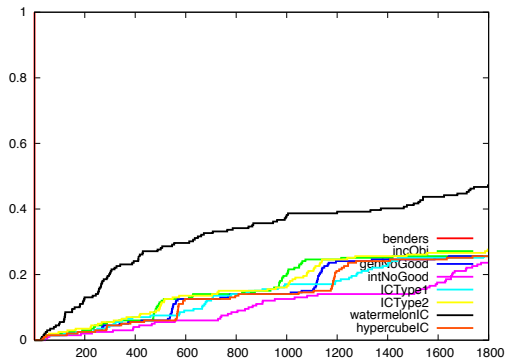


Figure: Performance profile with *solution time* as the performance measure

Computational Results

- Performance of different cuts on the instances of INTERD-DEN
- 199 instances that can be solved by at least one method in 3600 seconds and whose solution time exceeds 5 seconds for at least one method.
- Benders cut was not considered.

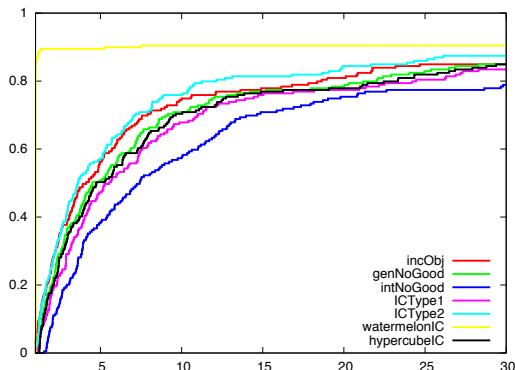


Figure: Performance profile with *solution time* as the performance measure

Computational Results

- Performance of different cuts on the instances of IBLP-DEN
- 23 instances that can be solved by at least one method in 3600 seconds and whose solution time exceeds 5 seconds for at least one method.

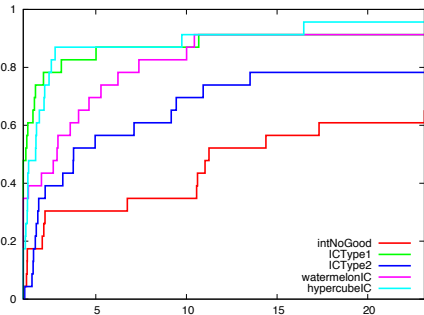


Figure: Performance profile with *solution time* as the performance measure

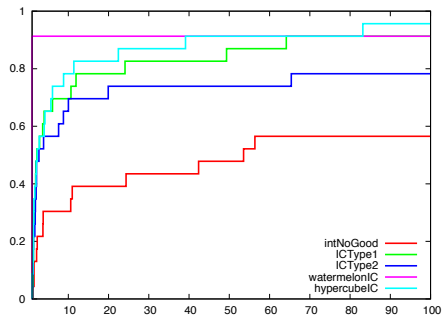


Figure: Performance profile with *number of nodes* as the performance measure

Computational Results

- Performance of different cuts on the instances of IBLP-XU
- 77 instances that can be solved by at least one method in 3600 seconds and whose solution time exceeds 5 seconds for at least one method.

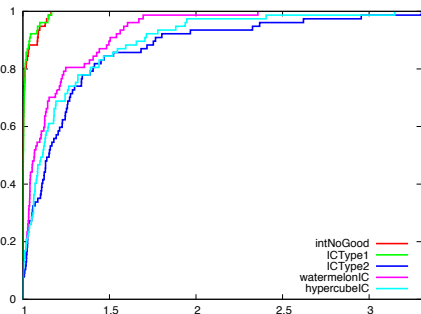


Figure: Performance profile with *solution time* as the performance measure

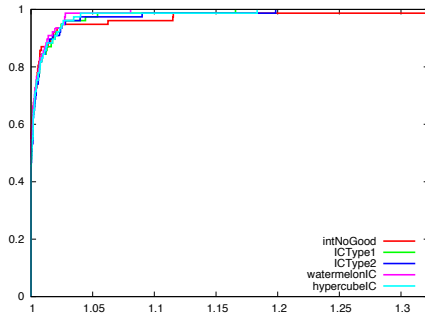


Figure: Performance profile with *number of nodes* as the performance measure

Computational Results

- Comparison of the rhs of different cuts with the best rhs
- 5 instances of INTERD-DEN with 20 variables were considered.

	Benders Cut		Watermelon IC		Integer No-good Cut	
	Orig RHS	Best RHS	Orig RHS	Best RHS	Orig RHS	Best RHS
1	-4520	-4520	-1	-1.65	-1	-7
2	-3917	-3917	-1	-1.27	-1	-6
3	-3334	-3334	-1	-1	-1	-6
4	-3915	-3915	-1	-1.01	-1	-6
5	-4924	-4924	-1	-1.01	-1	-6

Computational Results

- Impact of improving the rhs of integer no-good cut on the instances of IBLP-DEN
- 180 instances whose solution time is more than 5 seconds by using the integer no-good cut.

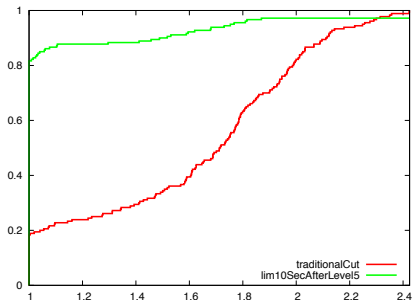


Figure: Performance profile with *solution time* as the performance measure

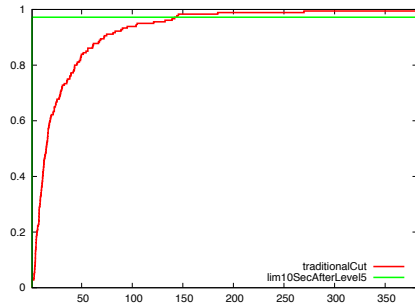


Figure: Performance profile with *number of nodes* as the performance measure

Computational Results

- Impact of improving the rhs of integer no-good cut on the instances of IBLP-DEN
- 14 instances whose solution time is more than 5 seconds by using the integer no-good cut.

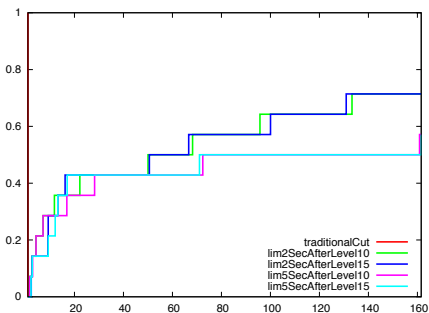


Figure: Performance profile with *solution time* as the performance measure

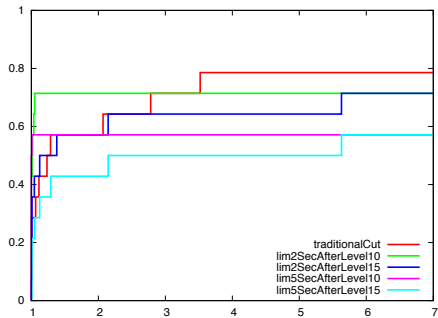


Figure: Performance profile with *number of nodes* as the performance measure

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Thank You!