

# Analysis of Parallel Algorithms

IE 496 Lecture 8

# Reading for This Lecture

- Paper by Kumar and Gupta
- Paper by Gustafson
- Roosta, Chapter 5

# Parallel Systems

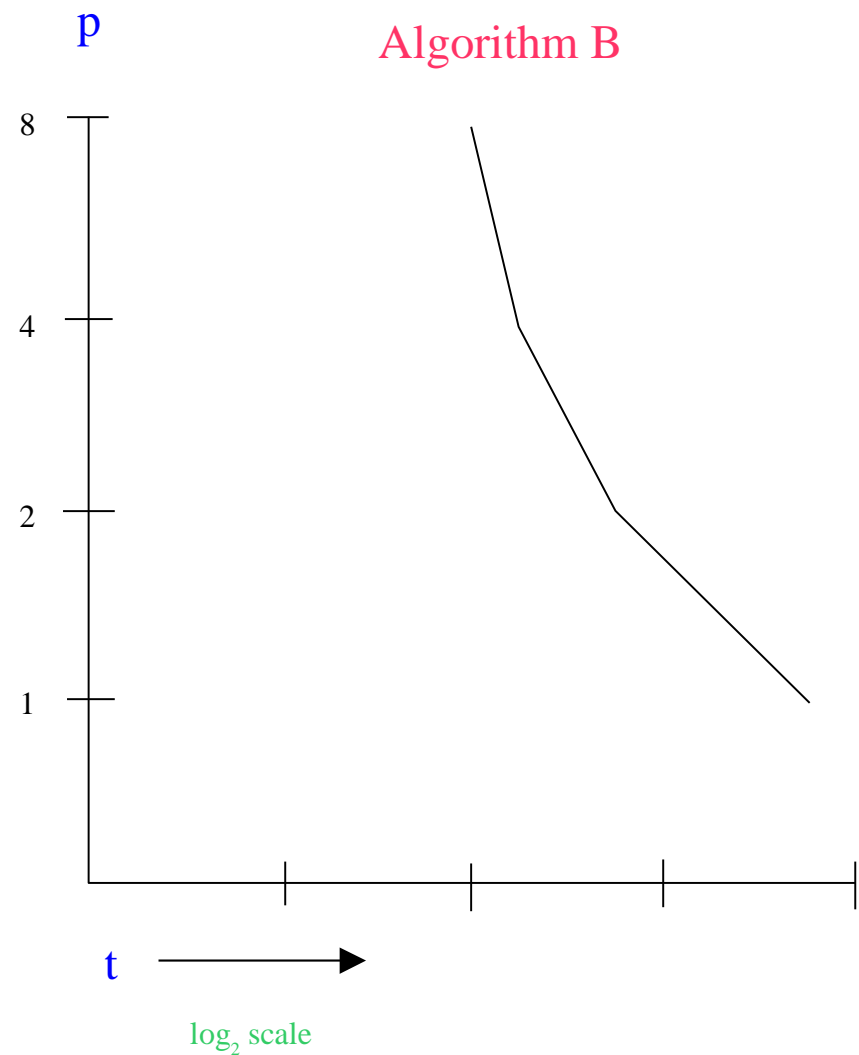
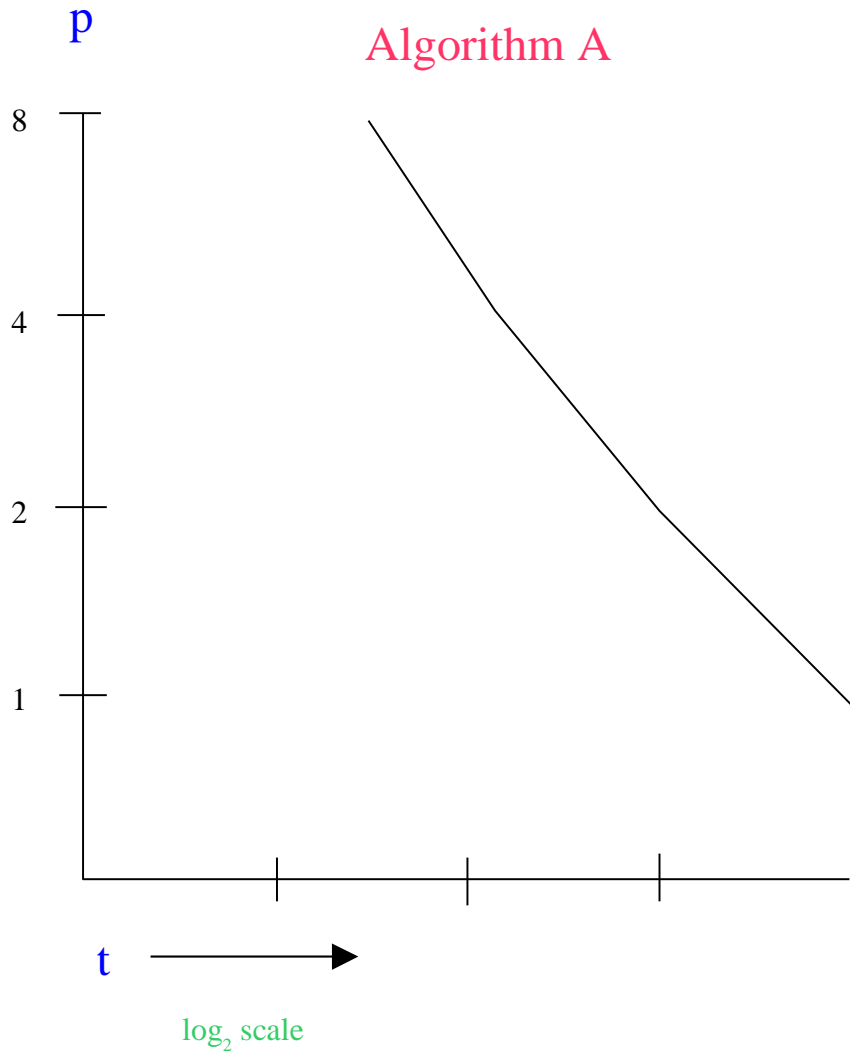
- A **parallel system** is a parallel algorithm plus a specified parallel architecture.
- Unlike sequential algorithms, parallel algorithms cannot be analyzed very well in isolation.
- One of our primary measures of goodness of a parallel system will be its **scalability**.
- **Scalability** is the ability of a parallel system to take advantage of increased computing resources (primarily more processors).

# Empirical Analysis of Parallel Algorithms

- Modern parallel computing platforms are essentially all asynchronous.
- Threads/processes do not share a global clock.
- In practice, this means that the execution of parallel algorithms is non-deterministic.
- For analysis of all but the simplest parallel algorithms, we must depend primarily on empirical analysis.
- The realities ignored by our models of parallel computation are actually important in practice.

# Scalability Example

Which is better?



# Terms and Notations

Sequential Runtime

$$T_1$$

Sequential Fraction

$$s$$

Parallel Fraction

$$p = 1 - s$$

Parallel Runtime

$$T_N$$

Cost

$$C_N = NT_N$$

Parallel Overhead

$$T_o = C_N - T_1$$

Speedup

$$S_N = T_1 / T_N$$

Efficiency

$$E = S_N / N$$

# Definitions and Assumptions

- The **sequential running time** is usually taken to be the running time of the best sequential algorithm.
- The **sequential fraction** is the part of the algorithm that is inherently sequential (reading in the data, splitting, etc.)
- The **parallel overhead** includes all additional work that is done due to parallelization.
  - communication
  - nonessential work
  - idle time

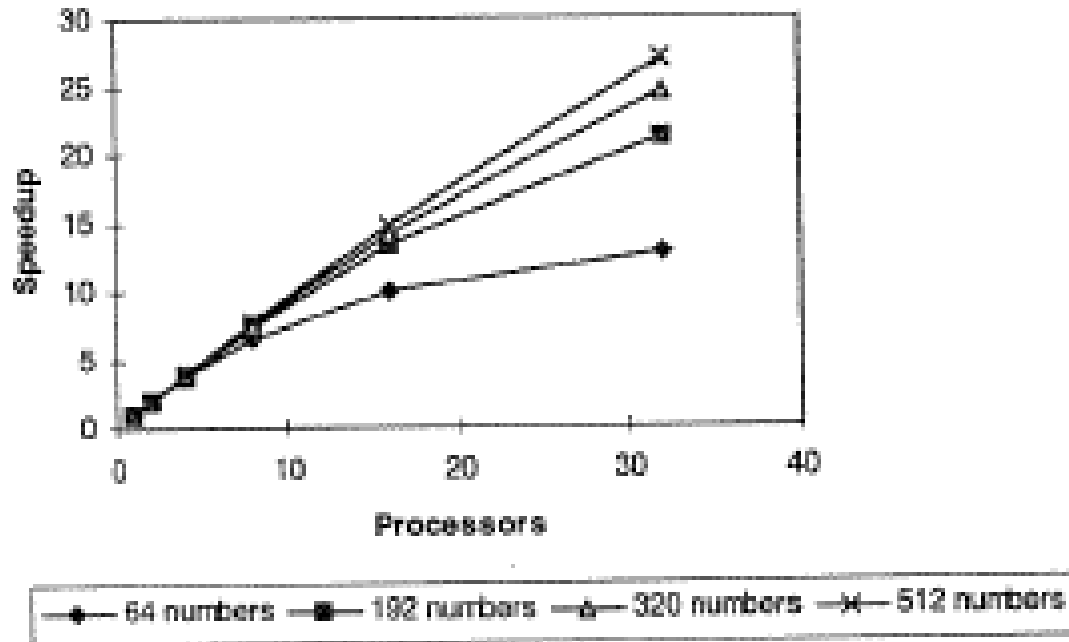
# Cost, Speedup, and Efficiency

- These three concepts are closely related.
- A parallel system is **cost optimal** if  $C_N \in O(T_1)$ .
- A parallel system is said to exhibit **linear speedup** if  $S \in O(N)$ .
- Hence, **linear speedup**  $\Leftrightarrow$  **cost optimal**  $\Leftrightarrow E = 1$
- If  $E > 1$ , this is called **super-linear speedup**.
- Superlinear speedup can arise in arise, though it it is not possible *in principle*.



# Example: Parallel Semi-group

- With  $n$  data elements and  $p$  processors, we first combine  $n/p$  elements sequentially locally.
- Then combine local results.
- Parallel running time is  $n/p + 2 \log p$ .



# Factors Affecting Speedup

- Sequential Fraction
- Parallel Overhead
  - Unnecessary/duplicate work
  - Communication overhead/idle time
  - Time to split/combine
- Task Granularity
- Degree of Concurrency
- Synchronization/Data Dependency
- Work Distribution
- Ramp-up and Ramp-down Time

# Amdahl's Law

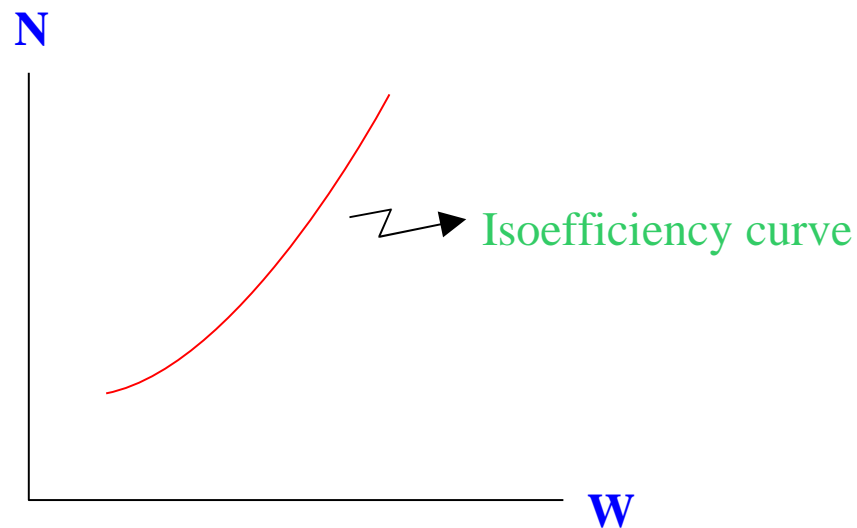
- Speedup is bounded by

$$(s + p)/(s + p/N) = 1/(s + p/N) = N/(sN + p)$$

- This means more processors  $\Rightarrow$  less efficient!
- How do we combat this?
- Typically, larger problem size  $\Rightarrow$  more efficient.
- This can be used to "overcome" Amdahl's Law.

# The Isoefficiency Function

- The **isoefficiency function**  $f(N)$  of a parallel system represents the rate at which the problem size must be increased in order to maintain a fixed efficiency



- This function is a measure of scalability that can be analyzed using asymptotic analysis.

# Gustafson's Viewpoint

- Gustafson noted that typically the serial fraction does not increase with problem size.
- This view leads to an alternative bound on speedup called **scaled speedup**.

$$(s + pN)/(s + p) = s + pN = N + (1-N)s$$

- This may be a more realistic viewpoint.