

# Integer Programming

## ISE 418

### Lecture 23

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## Reading for This Lecture

- Achterburg “Constraint Integer Programming” (2007)
- M.W.P. Savelsbergh “Preprocessing and Probing for Mixed Integer Programming Problems.”
- A. Atamturk, G. Nemhauser, and M.W.P. Savelsbergh, “Conflict Graphs in Solving Integer Programming Problems.”
- T. Achterberg, R.E. Bixby, Z. Gu, E Rothberg, And D. Weninger, “Presolving Reductions in Mixed Integer Programming.”

## Preprocessing and Probing

- Often, it is possible to **simplify** a model using logical arguments.
- Most commercial IP solvers have a built-in preprocessor.
- Effective preprocessing can pay large dividends.
- Let the upper and lower bounds on  $x_j$  be  $u_j$  and  $l_j$ .
- The most basic type of preprocessing is calculating *implied bounds*.
- Let  $(\pi, \pi_0)$  be a valid inequality.
- If  $\pi_1 > 0$ , then

$$x_1 \leq (\pi_0 - \sum_{j:\pi_j>0} \pi_j l_j - \sum_{j:\pi_j<0} \pi_j u_j) / \pi_1$$

- If  $\pi_1 < 0$ , then

$$x_1 \geq (\pi_0 - \sum_{j:\pi_j>0} \pi_j l_j - \sum_{j:\pi_j<0} \pi_j u_j) / \pi_1$$

## Basic Preprocessing

- Again, let  $(\pi, \pi_0)$  be any valid inequality for  $\mathcal{S}$ .
- The constraint  $\pi x \leq \pi_0$  is **redundant** if

$$\sum_{j:\pi_j>0} \pi_j u_j + \sum_{j:\pi_j<0} \pi_j l_j \leq \pi_0.$$

- $\mathcal{S}$  is empty (IP is **infeasible**) if

$$\sum_{j:\pi_j>0} \pi_j l_j + \sum_{j:\pi_j<0} \pi_j u_j > \pi_0.$$

- For any IP of the form  $\max\{cx \mid Ax \leq b, l \leq x \leq u\}, x \in \mathbb{Z}^n$ ,
  - If  $a_{ij} \geq 0 \forall i \in [1..m]$  and  $c_j < 0$ , then  $x_j = l_j$  in any optimal solution.
  - If  $a_{ij} \leq 0 \forall i \in [1..m]$  and  $c_j > 0$ , then  $x_j = u_j$  in any optimal solution.

## Probing for Integer Programs

- It is also possible in many cases to fix variables or generate new valid inequalities based on logical implications.
- Consider  $(\pi, \pi_0)$ , a valid inequality for 0-1 integer program.
- If  $\pi_k > 0$  and  $\pi_k + \sum_{j:\pi_j < 0} \pi_j > \pi_0$ , then we can fix  $x_k$  to zero.
- Similarly, if  $\pi_k < 0$  and  $\sum_{j:\pi_j < 0, j \neq k} \pi_j > \pi_0$ , then we can fix  $x_k$  to one.
- Example: Generating logical inequalities

## Generation of the Conflict Graph

- As describe earlier, a *conflict* is a pair of variables and associated values that are mutually incompatible.
- For example, we may derive that binary variables  $x_1$  and  $x_2$  cannot both take value 1 simultaneously.
- These conflicts can be generated in a number of ways:
  - during preprocessing;
  - during cut generation; or
  - when the LP relaxation is infeasible;
- Known conflicts can be stored as a *conflict graph* in which the nodes correspond to variable-value pairs and the edges correspond to conflicts.
- The graph can be used to guide branching decisions, fix variable values, etc.

## Improving Coefficients

- Suppose again that  $(\pi, \pi_0)$  is a valid inequality for a 0-1 integer program.
- Suppose that  $\pi_k > 0$  and  $\sum_{j:\pi_j>0, j\neq k} \pi_j < \pi_0$ .
- If  $\pi_k > \pi_0 - \sum_{j:\pi_j>0, j\neq k} \pi_j$ , then we can set
  - $\pi_k \leftarrow \pi_k - (\pi_0 - \sum_{j:\pi_j>0, j\neq k} \pi_j)$ , and
  - $\pi_0 \leftarrow \sum_{j:\pi_j>0, j\neq k} \pi_j$ .
- Similarly, suppose that  $\pi_k < 0$  and  $\pi_k + \sum_{j:\pi_j>0, j\neq k} \pi_j < \pi_0$ .
- Then we can again set  $\pi_k \leftarrow \pi_0 - \sum_{j:\pi_j>0, j\neq k} \pi_j$

## Preprocessing Based on Problem Structure

- Example: Preprocessing Methods in Set Partitioning
  - Duplicate columns
  - Dominated rows
  - Column is a sum of other columns
  - Extended row clique
  - Singleton row
  - Rows differ by two entries

## Preprocessing and Probing in Branch and Bound

- In practice, these rules are applied **iteratively** until none applies.
- Applying one of the rules may cause a new rule to apply.
- Rules that explicitly use the global lower bound can be reapplied whenever a new incumbent is found.
- Furthermore, all rules can be **reapplied** after branching.
- These techniques can make a very big difference.

## Root Node Processing

- Typically, more effort is put into processing the root node than other nodes in the tree.
- Work done in the root node will impact the processing of every subsequent node.
- Dual bounding
  - Cut generation in the root node can be thought of as an additional pre-processing step to strengthen the formulation before enumeration.
  - Cut generation in the root node can also be used to predict effectiveness of such techniques elsewhere in the tree.
- Primal bounding
  - Primal bounds found in the root node can have a big impact on the search.
  - They help to improvement variable bounds by reduced cost and can also lead to more effective/efficient search strategies.
  - As with cut generation, we use performance in the root node as an indicator of efficacy throughout the tree.

## Node Pre/Post-Processing: Bound Improvement by Reduced Cost

- Consider an integer program  $\max_{x \in \mathbb{Z}^n} \{cx \mid Ax \leq b, 0 \leq x \leq u\}$ .
- Suppose the linear programming relaxation has been solved to optimality and row zero of the tableau looks like

$$z = \bar{a}_{00} + \sum_{j \in NB_1} \bar{a}_{0j} x_j + \sum_{j \in NB_2} \bar{a}_{0j} (x_j - u_j)$$

where  $NB_1$  are the nonbasic variables at 0 and  $NB_2$  are the nonbasic variables at their upper bounds  $u_j$ .

- In addition, suppose that a lower bound  $\underline{z}$  on the optimal solution value for IP is known.
- Then in any optimal solution

$$x_j \leq \left\lfloor \frac{\bar{a}_{00} - \underline{z}}{-\bar{a}_{0j}} \right\rfloor \text{ for } j \in NB_1, \text{ and}$$

$$x_j \geq u_j - \left\lceil \frac{\bar{a}_{00} - \underline{z}}{\bar{a}_{0j}} \right\rceil \text{ for } j \in NB_2.$$

## Node Pre/Post-Processing: Other Techniques

- Bound improvement in the root node
  - Whenever a new lower bound is found by a heuristic or otherwise, we can apply bound improvement in the root node.
  - To do so, we save the reduced costs of the variables in the root node.
  - We can do this for multiple bases obtained during the processing of the root node.
  - The bound improvements found in this way can be immediately applied to all candidate and active nodes.
- Techniques similar to those applied in the root node can also be applied during the processing of individual nodes.
- New implications may be available once branching constraints are applied.

## Node Pre/Post-Processing: Conflict Analysis

- Whenever a node is found to be infeasible, we derive a *conflict*.
- The branching constraints imposed to arrive at that node cannot all be imposed simultaneously.
- These conflicts can be used to derive cuts and may also contribute to enhancement of the conflict graph.