

# Branching for Branch and Price Algorithm

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## Practical Issues: Branching Rules

- Branching must not destroy the structure of the subproblem.
- Branching should result child nodes that represent balanced sets of solutions which leads tighter bounds at each node.
- Original variable  $x$  is integer then,  $\sum_{q \in Q} q \lambda_q$  be integer.
- Typically, branching on individual master variable  $\lambda_q$  results unbalanced tree and significant subproblem modifications.

# Branching Rules and Cuts for Branch and Price Algorithm

- 1 Branching on and writing cuts in terms of master problem variables ( $\lambda$ ).
- 2 Implicit branching through pricing problem.
- 3 Branching on and writing cuts in terms of original variables ( $x$ ).

MP

$$\begin{aligned} \min \quad & \sum_{q \in Q} c_q \lambda_q \\ \text{s.t.} \quad & \sum_{q \in Q} A_q \lambda_q \geq b \quad (\pi) \\ & \sum_{q \in Q} \lambda_q \leq K \quad (v) \\ & \lambda_q \geq 0 \quad \forall q \in Q \end{aligned}$$

Pricing Problem

$$\begin{aligned} \min \quad & cy - \pi Ay + v \\ & Dy \geq d \\ & y \in \mathbb{N}^k \end{aligned}$$

- Branching on fractional  $\lambda_q$  is not appropriate. Because:
  - significant changes for sub problem,
  - unbalanced branch and bound tree.
- If master problem solution  $\lambda = (\lambda_1, \dots, \lambda_{|Q|})$  is fractional, then there exists  $\hat{Q} \subseteq Q$  such that

$$\sum_{q \in \hat{Q}} \lambda_q = \alpha, \quad \alpha \text{ is fractional.}$$

- Then we can write the branching rule:

$$\sum_{q \in \hat{Q}} \lambda_q \leq \lfloor \alpha \rfloor \quad \text{or} \quad \sum_{q \in \hat{Q}} \lambda_q \geq \lceil \alpha \rceil$$

Generic master formulation with branching rules:

$$\begin{aligned} \min \quad & \sum_{q \in Q} c_q \lambda_q \\ \text{s.t.} \quad & \sum_{q \in Q} A_q \lambda_q \geq b \quad (\pi) \\ & \sum_{q \in Q} \lambda_q \leq K^j \quad \text{for } j \in G^u \quad (\mu_j) \\ & \sum_{q \in Q} \lambda_q \geq L^j \quad \text{for } j \in H^u \quad (v_j) \\ & \lambda_q \geq 0 \quad \forall q \in Q \end{aligned}$$

Reduced cost of the column:

$$\bar{c}_q = c_q - \sum_{i=1}^m \pi_i a_{iq} + \sum_{j \in G^u} \mu_j g_j(q) - \sum_{j \in H^u} v_j h_j(q)$$

- $g_j(q) = 1$  if column  $q$  has a nonzero coefficient in the row  $j \in G^u$ .
- $h_j(q) = 1$  if column  $q$  has a nonzero coefficient in the row  $j \in H^u$ .

- Column Generation Subproblem:

$$\min \quad cy - \pi Ay + \mu g - vh$$

$$Dy \geq d$$

$$g = g(y)$$

$$h = h(y)$$

$$y \in \mathbb{N}^k$$

$$g \in \{0, 1\}^{|G^u|}$$

$$h \in \{0, 1\}^{|H^u|}$$

- $g = g(y), h = h(y)$  are boolean functions: **g=TRUE (=1)** if generated column  $y$  will have a positive coefficient in the corresponding branching constraint.

## Proposition

Given a feasible solution  $\lambda$  for master problem that is not integral, there exists a hyperplane  $(\gamma, \gamma_0) \in \mathbb{Z}^{n+1}$  such that  $\sum_{q \in Q: \gamma q \geq \gamma_0} \lambda_q$  is fractional.

- If master problem solution  $\lambda = (\lambda_1, \dots, \lambda_{|Q|})$  is fractional, then there exists  $(\gamma, \gamma_0) \in \mathbb{Z}^{n+1}$  such that

$$\sum_{q \in Q: \gamma q \geq \gamma_0} \lambda_q = \alpha, \quad \alpha \text{ is fractional.}$$

- The branching rule is

$$\sum_{q \in Q: \gamma q \geq \gamma_0} \lambda_q \leq \lfloor \alpha \rfloor \quad \text{or} \quad \sum_{q \in Q: \gamma q \geq \gamma_0} \lambda_q \geq \lceil \alpha \rceil$$



Let  $\mu_j$  be the dual variable for  $\sum_{q \in Q: \gamma q \geq \gamma_0} \lambda_q \leq [\alpha]$ :

- Reduced cost of a column changed to:

$$\bar{c}_q = c_q - \sum_{i=1}^m \pi_i a_{iq} + \mu_j g_j(q)$$

where  $g_j = 1$  if column  $q$  satisfy  $\gamma q \geq \gamma_0$ .

- The objective function of subproblem is updated with  $+\mu_j g_j$ .
- Since it is unattractive for objective function, it is enough to put a constraint to force  $g_j = 1$  when necessary.
- Constraint should be added to the subproblem to force  $g_j = 1$  when the column,  $q$  satisfy  $\gamma q \geq \gamma_0$ .
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$$(\gamma_{max}^j - \gamma_0^j + 1)g_j \geq \gamma^j q - \gamma_0^j + 1$$

where  $\gamma_{max}^j = \max_{q \in Q} \gamma^j q$

## Subproblem Modification: Cont.

Let  $v_j$  be the dual variable for  $\sum_{q \in Q: \gamma q \geq \gamma_0} \lambda_q \geq \lceil \alpha \rceil$ :

- Reduced cost of a column changed to:

$$\bar{c}_q = c_q - \sum_{i=1}^m \pi_i a_{iq} - v_j h_j(q)$$

where  $h_j = 1$  if column  $q$  satisfy  $\gamma q \geq \gamma_0$ .

- The objective function of subproblem is updated with  $-v_j h_j$ .
- Since it is attractive for objective function, it is enough to put a constraint to force  $h_j = 0$  when necessary.
- Constraint should be added to the subproblem to force  $h_j = 0$  when the column,  $q$  satisfy  $\gamma q < \gamma_0$ .
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$$(\gamma_0^j - \gamma_{min}^j) h_j \leq \gamma^j q - \gamma_{min}^j$$

where  $\gamma_{min}^j = \min_{q \in Q} \gamma^j q$

## Comments About the Rule

- Any fractional solution can be cut off.
- Number of possible sets is finite, the rule is finite.
- Complete branching rule.
- Not easy to find a hyperplane. Theoretical.
- In practice, consider hyperplanes with  $\gamma = e^i$ , but it does not guarantee the existence of hyperplanes.

# Implicit Branching Through Pricing Problem

- Subproblem finds shortest path from an origin (s) to a destination (t) with minimum cost.
- Columns in master problem represent paths (arc incidence vectors).
- Solution of master problem is a combination of these paths satisfying the constraints.
- Let  $q \in \{0, 1\}^n$  be the column vector where  $n$  is the number of arcs in the network. If the solution to the master problem is not integral, then there exists an arc  $k$  such that the flow along the arc

$$\sum_{q \in Q: q^k=1} = \lambda_q$$

is fractional.

## Branch 1

Flow on arc  $k = (a \rightarrow b)$  is equal to 1.

- Master Problem: set  $\lambda_q = 0$  for all  $\{q \in Q\}$  if  $\lambda_q$  should be zero if arc  $k$  is in the solution.
- Pricing Problem: delete all arcs into  $b$  and from  $a$  except arc  $a \rightarrow b$ .

## Branch 2

Flow on arc  $k = (a \rightarrow b)$  is equal to 0.

- Master Problem: set  $\lambda_q = 0$  for all  $\{q \in Q : q^k = 1\}$ .
- Pricing Problem: delete arc  $k$ .

## Example from Cutting Strip Problem

- $z_i^k$  = number of strips of width  $w_i$  cut from sheet  $k$ .
- $z_i^k = \sum_{q \in Q(k)} q_i^k \lambda_q$ .
- Let  $z_i^k$  be fractional and  $\lceil z_i^k \rceil = v$ .
- Force

$$\sum_{q \in Q(k): q_i^k \geq v} \lambda_q \in \{0, 1\}$$

- In any cutting pattern for sheet  $k$ , there must be at least  $v$  strips of width  $w_i$ .
- In master problem, remove columns that do not satisfy the rule.
- In pricing problem, set a lower bound for  $q_i^k$ .
- Generic constraints are explained in Vanderbeck (2000).

## Symmetric Structure

- Forcing the rule for sheet  $k_1 \rightarrow$  result columns for other sheets that do not satisfy the rule.
- Force:

$$\sum_{q \in Q: q_i \geq v} \lambda_q \text{ integer}$$

## Choosing $v$

- Poorly chosen  $v$  results uneven partition of the solution space.
- Partition interval  $[0, q_i^{max}]$  where  $q_i^{max}$  is the maximum value of  $q_i$  in any pattern.

Poggi and Uchoa (2003)<sup>1</sup> introduce **explicit master**:

## Reformulation

$$\begin{aligned} \min \quad & cx \\ x' - x &= 0 \\ Ax &= b \\ Dx' &\leq d \\ x', x &\in \mathbb{Z}_+^n \end{aligned}$$

## Explicit Master

$$\begin{aligned} \min \quad & cx \\ Q\lambda - x &= 0 \quad (\pi) \\ 1\lambda &= 1 \quad (v) \\ Ax &= b \quad (\mu) \\ \lambda, x &> 0 \end{aligned}$$

## Pricing Problem

$$\begin{aligned} \min \quad & -\pi x - v \\ Dx &\leq d \\ x &\in \mathbb{Z}_+^n \end{aligned}$$

- Size of explicit master is larger than DW master.
- LP relaxations are equal.
- Dual variable  $\mu$  corresponds to  $Ax = b$  is not used in pricing problem.
- Cuts in terms of  $x$  variables can easily be added to system  $Ax = b$ .

1. Poggi de Aragao, M., Uchoa, E.: Integer program reformulation for robust branch-and-cut-and-price. In: Annals of Mathematical Programming in Rio. Buzios, Brazil, 2003, pp.56.



Assume we have  $N$  subproblems. Possible strategies:

- Solve  $N$  problems pick the best improving column to enter RMP.
- Add all columns with negative reduced cost to the RMP.
- Solve  $N$  problems sequentially, e.g. solve 1, then 2, ..., solve  $N$ .
- Solve the subproblems by selecting randomly.
- Solve subproblem heuristically to generate quick columns.
- Use column pool to keep generated columns.
- Delete columns with positive reduced cost from RMP.